Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

# Gaussian Kinematic Formula and the integral geometry of random sets 

Jonathan Taylor<br>Stanford University

November 11, 2011

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Outline

- A model for random sets.
- Some old integral geometry.
- Gaussian integral geometry.
- Accuracy of approximation.


## Random sets

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Gaussian processes: basic building blocks

Twice-differentiable Gaussian process $\left(f_{t}\right)_{t \in M}$ on a manifold M.

Satisfying:

- $\mathbb{E}\left\{f_{t}\right\}=0$;
- $\mathbb{E}\left\{f_{t}^{2}\right\}=1$.


## Why Gaussian?

- Gaussian processes are specified by mean and covariance function.
- Finite-dimensional distributions are all simple multivariate Gaussian.


## Random sets

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Excursion sets

Random sets we will consider are of the form:

$$
f^{-1} A=\left\{t \in M: f_{t} \in A\right\}
$$

for $A \subset \mathbb{R}$. In particular, the geometry of these sets, and how it is determined by correlation function of $f$.

## Excursion above 0

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan
Taylor Stanford
University


## Excursion above 1

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University


## Excursion above 1.5

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan
Taylor Stanford
University


## Excursion above 2

Gaussian
Kinematic Formula and the integral geometry of random sets


## Excursion above 2.5

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan
Taylor Stanford
University


## Excursion above 3

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University


## Excursion above 3.3

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University


## Euler characteristic

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## What geometric features?

We're interested in integral geometric properties.
Specifically, the (expected) Euler characteristic

$$
\mathbb{E}\left\{\chi\left(f^{-1}[u,+\infty)\right)\right\}=\mathbb{E}\left\{\chi\left(M \cap f^{-1}[u,+\infty)\right)\right\}
$$

## EC tells you very little

Let $M$ be a 2-manifold without boundary, then

$$
\mathbb{E}\left\{\chi\left(M \cap f^{-1}[0,+\infty)\right)\right\}=\frac{1}{2} \cdot \chi(M)
$$

With boundary:

$$
\mathbb{E}\left\{\chi\left(M \cap f^{-1}[0,+\infty)\right)\right\}=\frac{1}{2} \cdot \chi(M)+\frac{1}{2 \pi} \cdot|\partial M|
$$

## Euler characteristic

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## EC is computable

Of all quantities in the studies of Gaussian processes, the EC stands out as being explicitly computable in wide generality

$$
\mathbb{E}\left\{\chi\left(M \cap f^{-1}[u,+\infty)\right)\right\}=\sum_{j=0}^{\operatorname{dim}(M)} \mathcal{L}_{j}(M) \rho_{j}(u) .
$$

Where do $\mathcal{L}_{j}$ 's and $\rho_{j}$ 's come from?
EC tells you a lot
For "nice enough" $M$

$$
\mathbb{E}\left\{\chi\left(M \cap f^{-1}[u,+\infty)\right)\right\} \stackrel{u \rightarrow \infty}{\sim} \mathbb{P}\left\{\sup _{t \in M} f_{t} \geq u\right\}
$$

## Euler characteristic

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Accuracy

- If the parameter set is locally convex, then

$$
\begin{gathered}
\left|\mathbb{P}\left\{\sup _{t \in M} f_{t} \geq u\right\}-\mathbb{E}\left\{\chi\left(M \cap f^{-1}[u,+\infty)\right)\right\}\right| \\
\stackrel{u \rightarrow \infty}{=} O_{\exp }\left(e^{-u^{2} / 2 \cdot\left(1+\frac{1}{\sigma_{( }^{2}(f)}\right)}\right)
\end{gathered}
$$

- Since, $\rho_{j}(u)=O_{\exp }\left(e^{-u^{2} / 2}\right)$, the approximation has exponential relative accuracy!


## Integral geometry

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Tube formulae

- Suppose $f$ is (the restriction to $M$ ) of an isotropic process $\tilde{f}$, with $\operatorname{Var}\left\{d \tilde{f} / d x_{i}\right\}=1$.
- For small $r$, the functionals $\mathcal{L}_{j}(M)$ are implicitly defined by Steiner-Weyl formula

$$
\mathcal{H}_{k}\left(x \in \mathbb{R}^{k}: d(x, M) \leq r\right)=\sum_{j=0}^{k} \omega_{k-j} r^{k-j} \mathcal{L}_{j}(M ; M)
$$

## Integral geometry: tubes

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

$\mathcal{H}_{3}(\operatorname{Tube}([0, a] \times[0, b] \times[0, c], r))$

$$
=a b c+2 r \cdot(a b+b c+a c)+\left(\pi r^{2}\right) \cdot(a+b+c)+\frac{4 \pi r^{3}}{3}
$$

## Integral geometry: tubes

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University


## Integral geometry: tubes

Gaussian Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Local convexity is important!

- Singularity means implicit definition is invalid, BUT $\mathcal{L}_{j}(\cdot)^{\prime}$ 's are still well defined..
- They are defined for a large class of sets ...



## Gaussian processes

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford
University


## Integral geometry: curvature measures

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University


## Integral geometry

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Kinematic Fundamental Formula

- Where else do we see $\mathcal{L}_{j}(\cdot)$ 's?




## Integral geometry

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Kinematic Fundamental Formula

- Considers the "average" curvature measures of $M_{1} \cap g M_{2}$, i.e.



## Integral geometry: KFF

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## The KFF on $\mathbb{R}^{N}$

- Isometry group $G_{N}$ of rigid motions of $\mathbb{R}^{N}$,

$$
G_{N} \sim \mathbb{R}^{N} \rtimes O(N)
$$

- Fix a Haar measure:

$$
\nu_{N}\left(\left\{g_{N} \in G_{N}: g_{N} x \in A\right\}\right)=\mathcal{H}_{N}(A)
$$

$$
\begin{aligned}
\int_{G_{N}} & \mathcal{L}_{i}\left(M_{1} \cap g_{N} M_{2}\right) d \nu_{N}\left(g_{N}\right) \\
& =\sum_{j=0}^{N-i}\left[\begin{array}{c}
i+j \\
i
\end{array}\right]\left[\begin{array}{c}
N \\
j
\end{array}\right]^{-1} \mathcal{L}_{i+j}\left(M_{1}\right) \mathcal{L}_{N-j}\left(M_{2}\right)
\end{aligned}
$$

## Back to Gaussian processes

Gaussian Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Analogy with KFF

- Recall what we were trying to study

$$
\begin{aligned}
\mathbb{E}\{\chi & \left.\left(M \cap f^{-1}[u,+\infty)\right)\right\} \\
& =\int_{\Omega} \mathcal{L}_{0}\left(M \cap f(\omega)^{-1}[u,+\infty)\right) \mathbb{P}(d \omega) \\
& =\sum_{j=0}^{\operatorname{dim}(M)} \mathcal{L}_{j}(M) \rho_{j}(u)
\end{aligned}
$$

- This looks like KFF on $\mathbb{R}^{N}$ where $g_{N} M_{2}$ is replaced by $f^{-1}[u,+\infty)=f^{-1} D$.
- Can replace $f$ with $f=\left(f_{1}, \ldots, f_{j}\right)$. Let's look at some examples...


## Gaussian processes: $D$ a cone

Gaussian
Kinematic Formula and the integral geometry of random sets Jonathan Taylor Stanford University


## Gaussian processes: $f^{-1} D$

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University


## Gaussian processes: $D$ a variety

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford
University


Gaussian processes: $f^{-1} D$

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University


## Gaussian processes

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Gaussian Kinematic Formula

- Let $f=\left(f_{1}, \ldots, f_{k}\right)$ be made of IID copies of a Gaussian field
- Consider the additive functional on $\mathbb{R}^{k}$ that takes a "rejection region"

$$
D \mapsto \mathbb{E}\left\{\chi\left(M \cap f^{-1} D\right)\right\} .
$$

- Questions: how do the $\mathcal{L}_{j}$ 's enter into this functional? How about D?


## Gaussian processes

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Gaussian Kinematic Formula

- Define the functionals $\mathcal{M}_{j}^{\gamma_{k}}(\cdot)$ implicitly by

$$
\gamma_{k}\left(y \in \mathbb{R}^{k}: d(y, D) \leq r\right)=\sum_{j \geq 0} \frac{(2 \pi)^{j / 2} r^{j}}{j!} \mathcal{M}_{j}^{\gamma_{k}}(D) .
$$

- Then:

$$
\mathbb{E}\left\{\chi\left(M \cap f^{-1} D\right)\right\}=\sum_{j} \mathcal{L}_{j}(M) \cdot \mathcal{M}_{j}^{\gamma_{k}}(D)
$$

## Integral geometry: curvature measures

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University


Q: How do we compute $\mathcal{M}_{j}^{\gamma_{k}}(\cdot)$ ?

## Integral geometry: curvature measures

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University


A: Integrate power series expansion for density over hypersurface at distance $r$...

## Example: linear statistic

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan
Taylor Stanford
University


## Example: $\chi^{2}$ statistic

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan
Taylor Stanford
University


## Examples

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## EC densities

- Gaussian EC densities

$$
\rho_{j}(u)=(-1)^{j} \frac{d^{j}}{d u^{j}} \mathbb{P}\{N(0,1)>u\}
$$

- $\chi_{k}^{2}$ EC densities

$$
\rho_{j, \chi_{k}^{2}}(u)=\left.(-1)^{j} \frac{d^{j}}{d x^{j}} \mathbb{P}\left\{\sqrt{\chi_{k}^{2}}>x\right\}\right|_{x=\sqrt{u}}
$$

## $t$ or $F$ statistic

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan
Taylor Stanford
University


## $t$ or $F$ statistic

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan
Taylor Stanford University

$\eta_{U}$

## Ideas behind the proof

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Hidden embedding

- A Gaussian process is just a mapping

$$
t \mapsto f_{t} \in L^{2}(\Omega, \mathcal{F}, \mathbb{P})
$$

- Our assumptions about mean and variance implies the image is in the unit sphere in $L^{2}(\Omega, \mathcal{F}, \mathbb{P})$, and it is an embedding.
- This suggests that the relevant "geometry" to prove this result is spherical.
- Short answer: yes.


## Proof: spherical KFF

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Spherical KFF

- For $\kappa \in \mathbb{R}$ define

$$
\mathcal{L}^{\kappa}(\cdot)=\sum_{n=0}^{\infty} \frac{(-\kappa)^{n}}{(4 \pi)^{n}} \frac{(i+2 n)!}{n!i!} \mathcal{L}_{i+2 n}(\cdot) .
$$

- For $M_{1}, M_{2} \subset S_{n^{1 / 2}}\left(\mathbb{R}^{n}\right)$

$$
\begin{aligned}
\int_{G_{n}} & \mathcal{L}_{i}^{n^{-1}}\left(M_{1} \cap g_{n} M_{2}\right) d \nu_{n, \lambda}\left(g_{n}\right) \\
& =\sum_{j=0}^{n-1-i}\left[\begin{array}{c}
i+j \\
i
\end{array}\right]\left[\begin{array}{c}
n-1 \\
j
\end{array}\right]^{-1} \mathcal{L}_{i+j}^{n^{-1}}\left(M_{1}\right) \mathcal{L}_{n-1-j}^{n^{-1}}\left(M_{2}\right)
\end{aligned}
$$

where $G_{n}=O(n)$, appropriately normalized.

## Proof: Poincaré's limit

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Model process

- For $M \subset S\left(\mathbb{R}^{j}\right)$ define a $\mathbb{R}^{k}$ valued process

$$
f^{n}\left(t, g_{n}\right)=\pi_{k}\left(n^{1 / 2} g_{n} t\right)
$$

where $g_{n} \in O(n)$ is a Haar-distributed random matrix and $\pi_{k}: S_{n^{1 / 2}}\left(\mathbb{R}^{n}\right) \rightarrow \mathbb{R}^{k}$ is projection onto the first $k$ coordinates.

- Poincaré's limit (and generalizations) ensures that the process $f^{n}=\left(f_{1}^{n}, \ldots, f_{k}^{n}\right)$ converges in variation to a vector of IID zero mean, unit variance Gaussian processes $f=\left(f_{1}, \ldots, f_{k}\right)$.


## Proof: connecting Gaussian processes with KFF

Gaussian
Kinematic Formula and the integral geometry of random sets

Jonathan Taylor Stanford University

## Expected EC for model process

- For $D \subset \mathbb{R}^{k}$

$$
\begin{aligned}
\int_{G_{n}} & \mathcal{L}_{i}^{1}\left(M \cap\left(f^{n}\right)^{-1}(D)\right) d \nu_{n, \lambda}\left(g_{n}\right) \\
& =n^{-i / 2} \int_{G_{n}} \mathcal{L}_{i}^{n^{-1}}\left(n^{1 / 2} M \cap \pi_{k}^{-1} D\right) d \nu_{n, \lambda}\left(g_{n}\right) \\
& =c_{n} \sum_{j=0}^{n-1-i}\left[\begin{array}{c}
i+j \\
i
\end{array}\right]\left[\begin{array}{c}
n-1 \\
j
\end{array}\right]^{-1} \mathcal{L}_{i+j}^{1}(M) \mathcal{L}_{n-1-j}^{n^{-1}}\left(\pi_{k}^{-1} D\right)
\end{aligned}
$$

- The set $\pi_{k}^{-1} D$ is the disjoint union of a warped product and $D \cap S_{n^{1 / 2}}\left(\mathbb{R}^{k}\right)$. Need to analyse curvatures of warped product asymptotically.
- The rest is combinatorics . . . almost.

