1154-68-1742Benjamin Rossman*, Bahen Centre for Information Technology, Room 6214, Toronto, ON
M5S2E4, Canada. Choiceless Polynomial Time.

The choiceless computation model of Blass, Gurevich and Shelah (1999, 2022) is an algorithmic framework for computing isomorphism-invariant properties of unordered structures. Machines in this model have the power of parallel execution, but lack the ability to make arbitrary choices. For example, a choiceless algorithm cannot freely select an arbitrary neighbor of a vertex in an unordered graph, but may execute a subroutine in parallel over all neighbors. In this talk, I will give an overview of results in the choiceless model and discuss the intriguing open question whether every polynomial-time graph property admits a choiceless poly-time algorithm. (Received September 16, 2019)